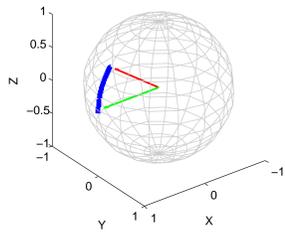


General and continuous quantum measurements



- ▶ Finite-dimensional quantum systems are represented by vectors in a Hilbert space $|\psi\rangle$
- ▶ Quantum states have continuous-time dynamics given by the Schrödinger equation $i\hbar\partial_t|\psi\rangle = H|\psi\rangle$ where H is a *Hamiltonian*
- ▶ General quantum measurements can disturb quantum states discontinuously and are defined by a set of measurement operators $\{M_k\}$ with $\sum_k M_k^\dagger M_k = I$ and $|\psi\rangle \xrightarrow{\text{prob. } p_k} \frac{M_k|\psi\rangle}{\sqrt{p_k}}$ where $p_k = \langle\psi|M_k^\dagger M_k|\psi\rangle$

Why study continuous quantum measurements?

Theoretical consideration

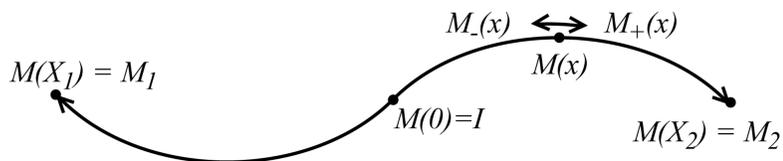
Quantum dynamics are reversible, deterministic and continuous. However, quantum measurements are irreversible, non-deterministic, and discontinuous. Can we describe measurements continuously but allow for irreversible, non-deterministic outcomes?

Experimental considerations

Many quantum mechanical systems either have naturally slow measurement times, or can only be probed weakly. For example: microwave cavities [BHL⁺90], homo- and heterodyne measurements in quantum optics [YIM86, SSH⁺87]

Continuous decompositions as random walks

In [OB05] it was shown that any quantum measurement $\{M_1, M_2\}$ can be decomposed into a 1-dimensional continuous stochastic process



In this scheme successive weak measurements (steps) $M_{\pm}(x)$ are applied at each time-step. These step operators are a function of the running total of measurement outcomes, the pointer variable x . This process can be seen as a 1-d random walk on a curve in operator space. The total walk operator $M(x)$ describes the evolution which terminates at the desired operators M_1 or M_2 .

Total walk operator	$M(x) \propto \lim_{\delta \rightarrow 0} \prod_{j=1}^{\lfloor x/\delta \rfloor} M_{\pm}(\pm j\delta)$
Endpoint operators	$M_{1,2} = \lim_{x \rightarrow X_{1,2}} M(x)$
Reversibility equation	$M_{\mp}(x \pm \delta)M_{\pm}(x) \propto \mathbb{1}$

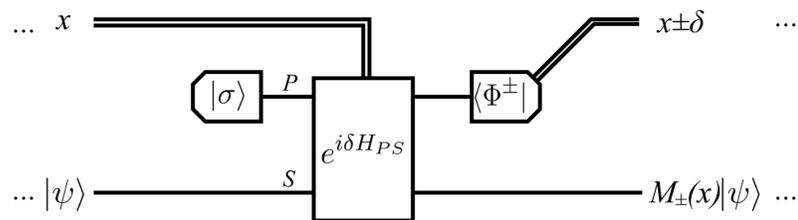
In [FB14] we've shown that any qubit-probe interacting in a fixed way with the system being measured can only decompose measurements of the form

$$M_1 = U_1 (\alpha \Pi_S + \beta \Pi_{S^\perp}) V$$

$$M_2 = U_2 (\sqrt{1 - \alpha^2} \Pi_S + \sqrt{1 - \beta^2} \Pi_{S^\perp}) V$$

Continuous decomposition with sequences of probes

New question: What can be done with a qubit-probe and a tunable interaction Hamiltonian?



In the above circuit we define the probe state $|\sigma(x)\rangle = |0\rangle$, the detector state $\langle\phi^\pm| = \langle\pm|$ and the tunable interaction

$$H_{PS} = Y_P \otimes \hat{\varepsilon}(x) \quad \hat{\varepsilon}(x) = \sum_{i=0}^d p_i(x) H_i$$

Step operators	$M_{\pm}(x) = \frac{1}{\sqrt{2}} \mathbb{1} + i\delta (\pm H_{PS}(x) 0\rangle$
Total walk operator	$M(x) = \sum_{i=1}^D a_i(x) H_i$

In addition to the reversibility equation, we also introduce

Operator propagation	$\partial_x M(x) = -\hat{\varepsilon}(x) M(x)$
----------------------	--

Quadratic systems of ODEs over non-associative algebras

The reversibility equation and the operator propagation equation can be rewritten as quadratic systems of ODEs

$$\text{Quadratic ODE sys. (1)} \quad \sum_{k=0}^d \partial_x p_k(x) H_k = \frac{1}{2} \sum_{i,j=0}^d p_i(x) p_j(x) \{H_i, H_j\}$$

$$\text{Quadratic ODE sys. (2)} \quad \sum_{k=0}^d \partial_x a_k(x) H_k = -\frac{1}{2} \sum_{i,j=0}^d p_i(x) a_j(x) H_i H_j$$

Closure lemma

In order to satisfy the reversibility equation, the span of linear control terms

$$F = \text{span} \{H_i\}$$

must be closed under anti-commutation

$$H_i \circ H_j := H_i H_j + H_j H_i \in F \quad \forall H_i, H_j \in F.$$

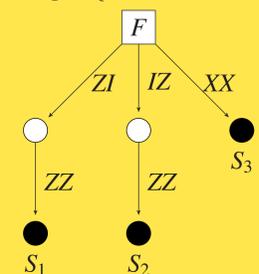
Restriction algorithm

```
function RESTRICT(F)
  if F^{\circ 2} = F then return F
  else
    S ← BASIS(F^{\circ 2})
    for all s ∈ S do
      s ← RESTRICT(F \setminus s)
    end for
  return S
end if
end function
```

In the example, we show the branching calls to RESTRICT(F). At each branch, we show which control term is dropped. The algorithm terminates on the filled nodes.

Example

INPUT: $F = \text{span} \{II, ZI, IZ, ZZ, XX\}$



RESTRICT(F) = $\{S_1, S_2, S_3\}$
 $S_1 = \{II, IZ, XX\}$
 $S_2 = \{II, ZI, XX\}$
 $S_3 = \{II, ZI, IZ, ZZ\}$

Extension algorithm

```
function EXTEND(F)
  while F^{\circ 2} \supset F do
    F ← BASIS(F^{\circ 2})
  end while
end function
```

Example

INPUT: $F = \text{span} \{II, ZI, IZ, ZZ, XX\}$
 EXTEND(F) = $\text{span} \{II, ZI, IZ, ZZ, XX, YY\}$

In this example we see that the only additional control term needed to complete the algebra was YY

Discussion

- ▶ Using the control set $F = \text{span} \{I, X, Z\}$ we can only decompose measurements of the form achieved by qubit-probe feedback above.
- ▶ Quadratic ODE system (2) is completely determined by system (1) and the initial condition $M(0) = I$.
- ▶ Quadratic ODE system (1) contains no orbits [KS95].
- ▶ The performance of RESTRICT(F) is sub-optimal, this is due to the freedom of choice for BASIS(F^{\circ 2})
- ▶ If the span of controls F is also closed under

$$H_1 H_2 H_3 H_4 + H_4 H_3 H_2 H_1 \in F$$

then by the *Cohn Reversible Theorem* F is the Hermitian part of the Free algebra generated by F (i.e.: the most general algebra). [McC04]

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